

# So what did happen on Tristan da Cunha?

Anton Camacho

Thesis: Stochastic modelling in epidemiology  
with applications to human influenza



Under the supervision of  
Bernard Cazelles and Amaury Lambert

# Contents

## Introduction

## Methods

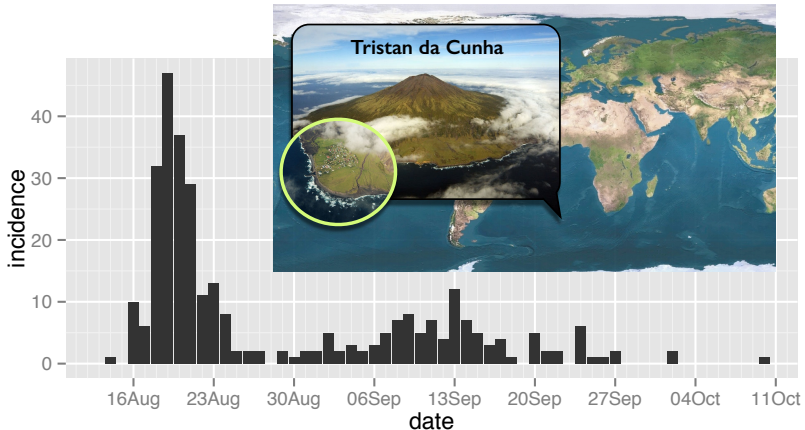
Modelling

Inference

## Results

Model inference & selection

# 1971 influenza epidemic on Tristan da Cunha



Two waves, 96% infected, 32% reinfected

Mantle and Tyrrell (1973)

## Broader context

- Influenza usually spreads through the human population in multiple-wave outbreaks.
- Successive reinfection of individuals over a short time interval has been explicitly reported during past pandemics.

Cross-Protection between Successive Waves of the 1918–1919 Influenza Pandemic: Epidemiological Evidence from US Army Camps and from Britain

John M. Barry,<sup>1</sup> Cécile Viboud,<sup>2</sup> and Lone Simonsen<sup>3</sup>

2008 *J Infect Dis*

**Pandemic (H1N1)  
2009 Reinfection,  
Chile**

Carlos M. Perez,  
Marcela Ferres,  
and Jaime A. Labarca

2010 *Emerg Infect Dis*



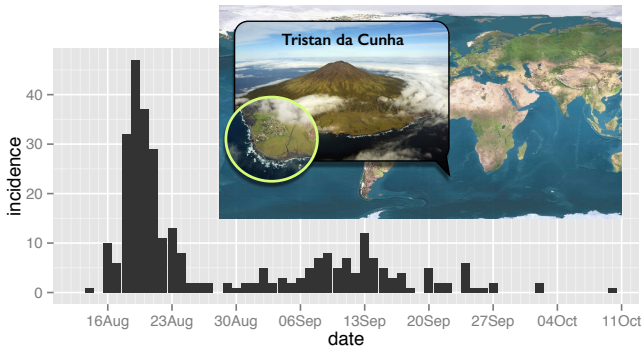
## Broader context

- Influenza usually spreads through the human population in multiple-wave outbreaks.
- Successive reinfection of individuals over a short time interval has been explicitly reported during past pandemics.

### Problematic

The *causes* of rapid reinfection and the *role* of reinfection in driving multiple-wave outbreaks remain poorly understood.

# Case study



## Objectives

- Disentangling between 5 biological mechanisms that could explain rapid reinfection of the islanders
- Assess how well the most likely mechanism can reproduce the data

# Contents

Introduction

**Methods**

Modelling

Inference

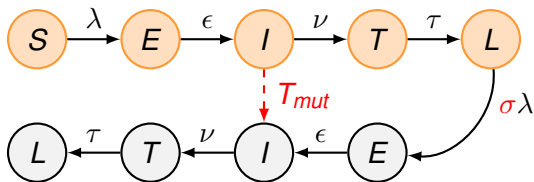
Results

Model inference & selection





# Mechanistic modelling of reinfection hypotheses



Primary immune response to influenza

**Mut** the virus Mutated during the first wave

2Vi 2 Viruses since the beginning of the epidemic

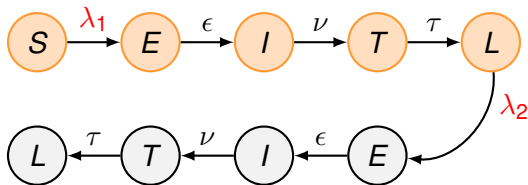
InH Intra-Host reinfection

PPI Partially Protective Immunity

AoN All or Nothing (the SEITL model in the practical)

Win Window of reinfection

# Mechanistic modelling of reinfection hypotheses



Primary immune response to influenza

Mut the virus Mutated during the first wave

**2Vi** 2 Viruses since the beginning of the epidemic

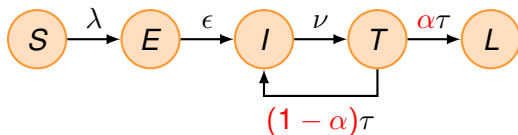
InH Intra-Host reinfection

PPI Partially Protective Immunity

AoN All or Nothing (the SEITL model in the practical)

Win Window of reinfection

# Mechanistic modelling of reinfection hypotheses



Primary immune response to influenza

Mut the virus Mutated during the first wave

2Vi 2 Viruses since the beginning of the epidemic

**InH** Intra-Host reinfection

PPI Partially Protective Immunity

AoN All or Nothing (the SEITL model in the practical)

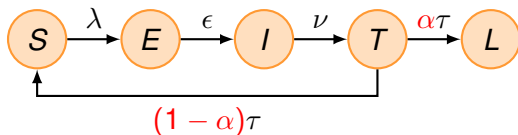
Win Window of reinfection







# Mechanistic modelling of reinfection hypotheses



Primary immune response to influenza

Mut the virus Mutated during the first wave

2Vi 2 Viruses since the beginning of the epidemic

InH Intra-Host reinfection

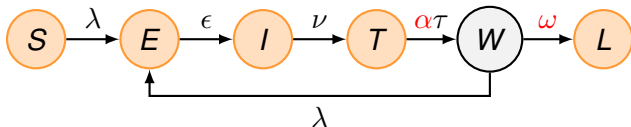
PPI Partially Protective Immunity

**AoN** All or Nothing (the SEITL model in the practical)

Win Window of reinfection



# Mechanistic modelling of reinfection hypotheses



Primary immune response to influenza

Mut the virus Mutated during the first wave

2Vi 2 Viruses since the beginning of the epidemic

InH Intra-Host reinfection

PPI Partially Protective Immunity

AoN All or Nothing (the SEITL model in the practical)

**Win** Window of reinfection

# Likelihood approach

For a given **time series**:  $y_{1:T} = (y_1, y_2, \dots, y_T)$  and a **state space model** completely specified by:

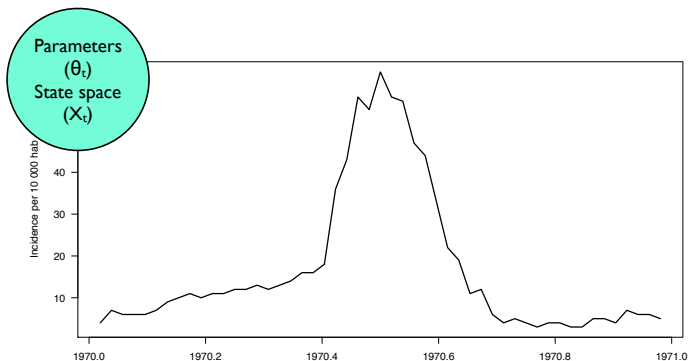
$$M : \begin{cases} p(x_t|x_{t-1}, \theta) & \text{fitmodel\$simulate} \\ p(y_t|x_t, \theta) & \text{fitmodel\$pointLogLike} \\ p(x_0|\theta) & \text{init.state now depends on } \theta \end{cases}$$

the **likelihood** is given by the identity:

$$p(y_{1:T}|\theta) = \prod_{t=1}^T p(y_t|y_{1:t-1}, \theta)$$

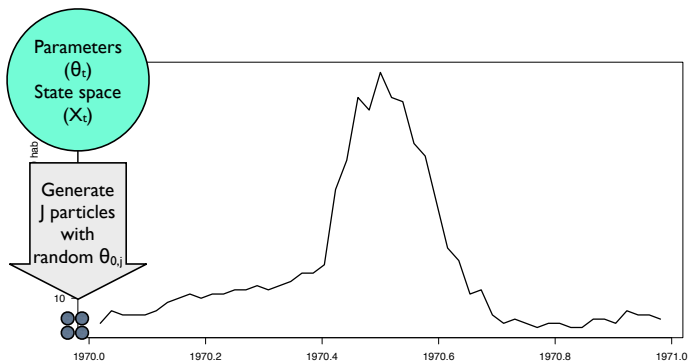
How can we find  $\theta_{\text{MLE}}$  that maximises the likelihood?

# Iterated Filtering (Ionides et al., 2006)



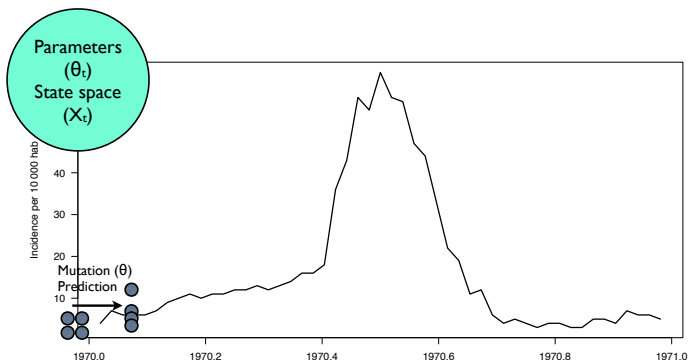
$$M \begin{cases} f(x_t|x_{t-1}, \theta) \\ f(y_t|x_t, \theta) \\ f(x_0|\theta) \end{cases} \quad \longrightarrow \quad M' \begin{cases} f(x_t|x_{t-1}, \theta_t) \\ f(y_t|x_t, \theta_t) \\ f(x_0|\theta_t) \end{cases}$$

# Iterated Filtering (Ionides et al., 2006)





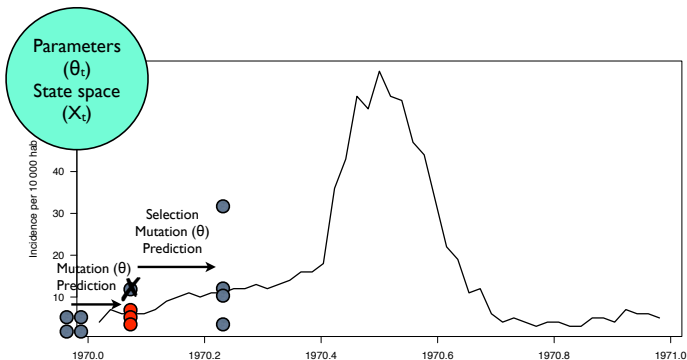
# Iterated Filtering (Ionides et al., 2006)



For each particle  $j$  :

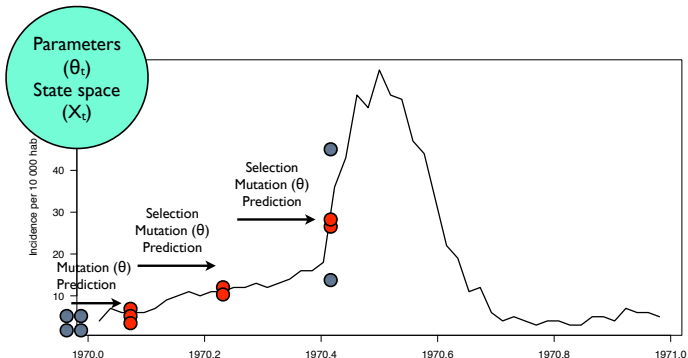
$$\begin{cases} X_{1,j} & \text{is drawn from } f(x_1|x_0 = X_{0,j}, \theta_{0,j}) \\ \theta_{1,j} & \text{is drawn from } \mathcal{N}(\theta_{0,j}, \sigma) \\ w_{1,j} & \text{is equal to } f(y_1|x_1 = X_{1,j}, \theta_{1,j}) \end{cases}$$

# Iterated Filtering (Ionides et al., 2006)



Darwinian selection: particles reproduce proportionally to their weight  $w_j$

# Iterated Filtering (Ionides et al., 2006)



Selection + Mutation + Prediction

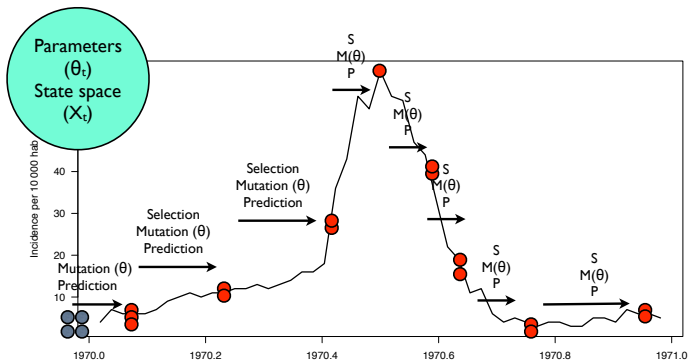








## Iterated Filtering (Ionides et al., 2006)

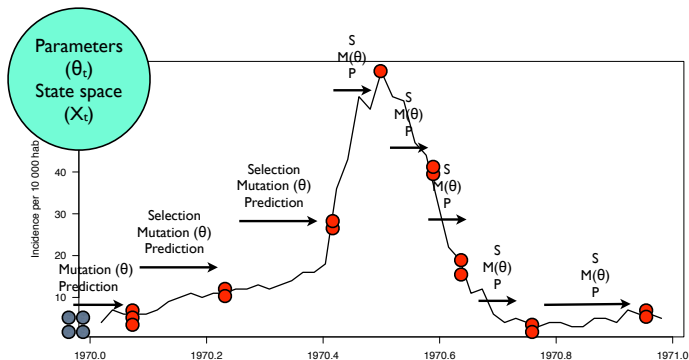


Punctual estimates for each time  $t$  from  $\{(\theta_{t,j}, w_{t,j})\}_J$

$$\left\{ \begin{array}{ll} E[\theta_t | y_{1:t}] & \text{by } \hat{\theta}_t \\ \text{Var}(\theta_t | y_{1:t-1}) & \text{by } V_t \\ f(y_t | y_{1:t-1}, \theta) & \text{by } l_t(\theta) = \frac{1}{J} \sum_J w_{t,j} \end{array} \right.$$



# Iterated Filtering (Ionides et al., 2006)



$$\text{Global estimate: } \hat{\theta} = \hat{\theta}_0 + V_1 \sum_{t=1}^T \frac{\hat{\theta}_t - \hat{\theta}_{t-1}}{V_t}$$

$$\text{Log-likelihood: } \mathcal{L}(\hat{\theta}) = \log(\prod_T l_t(\theta))$$



# Convergence of global estimator

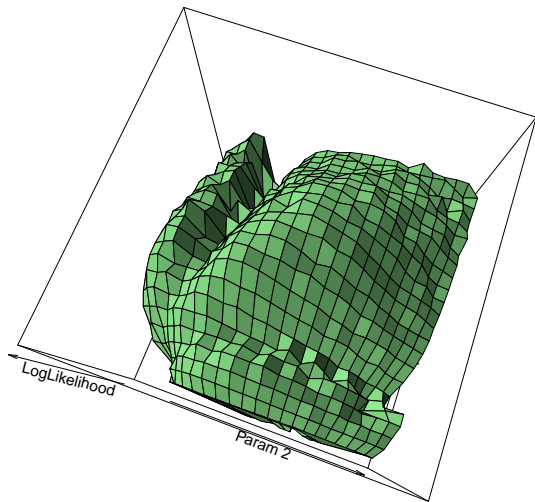
$$\hat{\theta}^{(n)} = \hat{\theta}^{(n-1)} + V_1^{(n)} \sum_{t=1}^T \frac{\hat{\theta}_t^{(n)} - \hat{\theta}_{t-1}^{(n)}}{V_t^{(n)}}$$

As shown by Ionides *et al.* (2006), under rather mild assumptions,

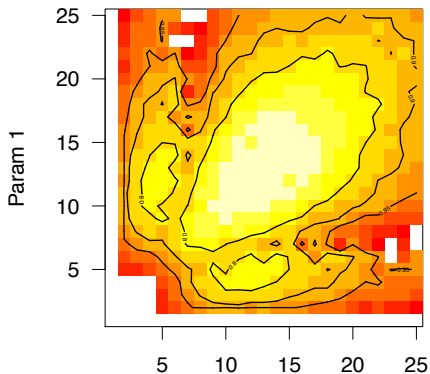
$$\lim_{\sigma \rightarrow 0} \sum_{t=1}^T \frac{\hat{\theta}_t - \hat{\theta}_{t-1}}{V_t} = \nabla \log f(y_{1:T} | \theta, \sigma = 0)$$

so that, for a sufficiently small  $\sigma_n$ , the algorithm iteratively updates  $\hat{\theta}^{(n)}$  in the direction of increasing likelihood, with a fixed point at a **local maximum of the likelihood surface**.

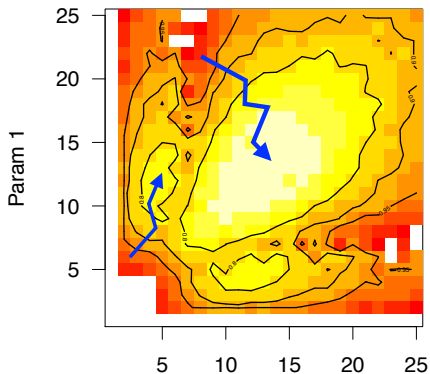
# Exploring the likelihood surface



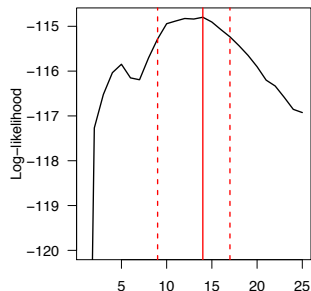
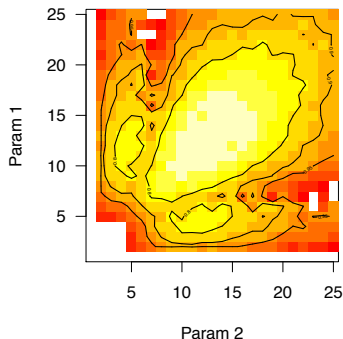
# Exploring the likelihood surface



# Exploring the likelihood surface

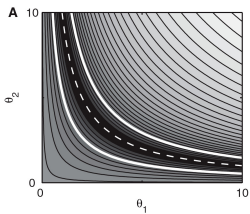


# Exploring the likelihood surface

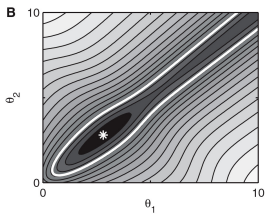


Log-likelihood profiles allows us to compute 95% *confidence* intervals.

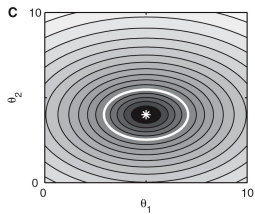
# Identifiability issues



Structural  
non-identifiability



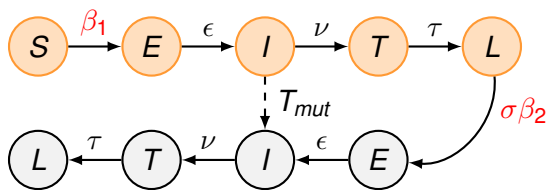
Practical  
non-identifiability



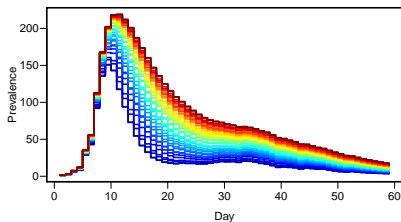
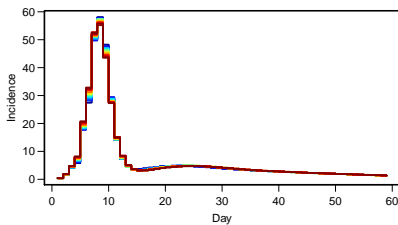
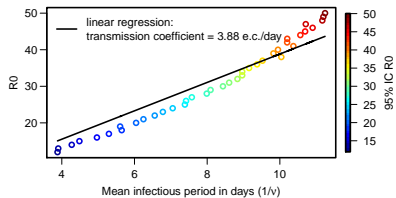
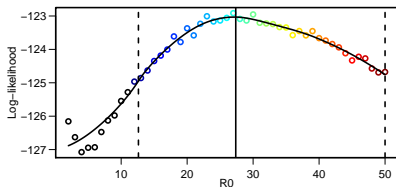
Identifiability



# Identifiability issues



# Identifiability issues



# Contents

Introduction

Methods

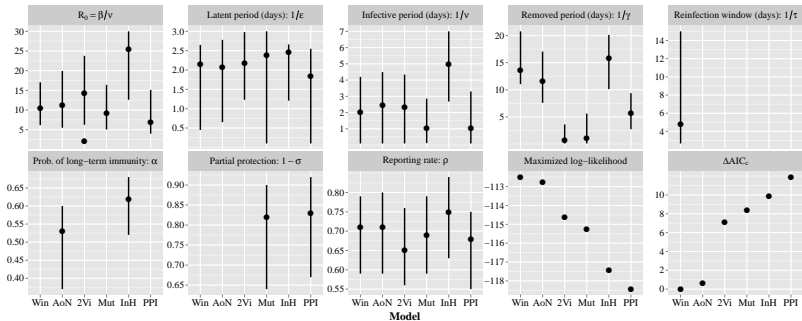
Modelling

Inference

Results

Model inference & selection

# Parameter inference



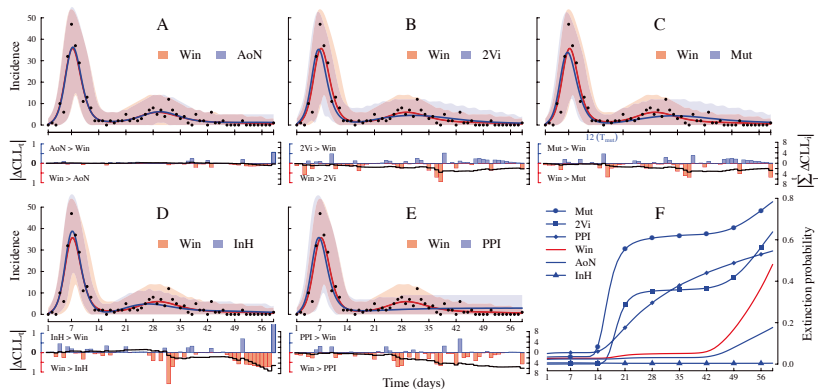
# Model selection

- We used the corrected Akaike Information Criterion ( $AIC_c$ ) to select the best model

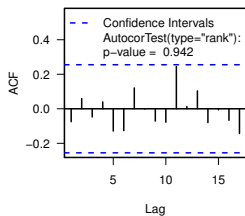
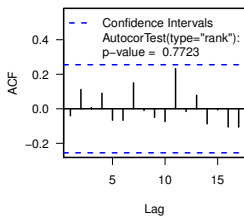
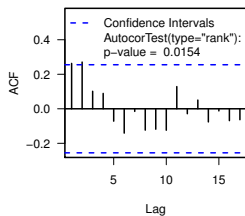
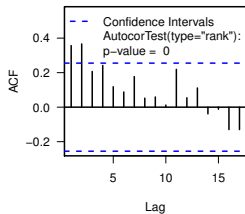
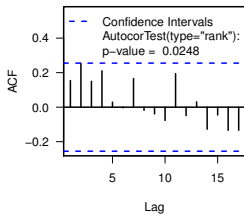
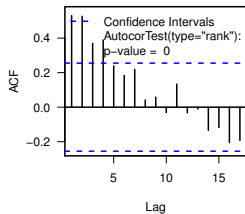
$$AIC_c = -2\mathcal{L}(\theta_{MLE}) + 2k + \frac{2k(k+1)}{T-k-1} \text{ with } k = \|\theta\|$$

- The best model corresponds to the Windows of reinfection hypothesis.
- The AoN (SEITL in the practical) model has substantial support ( $\Delta AIC_c < 2$ ).
- The other models have considerably less support ( $\Delta AIC_c > 7$ )

## Assess the fit



# Autocorrelation of the residuals

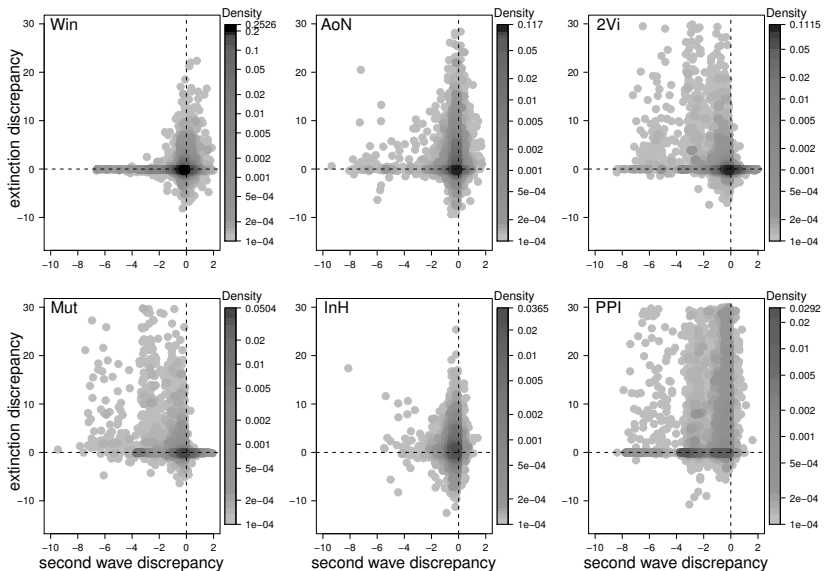
**Win****AoN****2Vi****Mut****InH****PPI**

# Posterior predictive checks

- Pick one or more summary-statistics of the time-series
- Compute their distances between model and data
- Do it for 10000 replicates of the model under  $\theta_{MLE}$



# Posterior predictive checks



# Posterior predictive checks

Proportion of points within a radius  $R$  from  $(0, 0)$ :

Model	$R = 0.25$	$R = 0.5$	$R = 1$	$R = 2$
<i>Win</i>	0.26	0.5	0.7	0.81
<i>AoN</i>	0.12	0.26	0.43	0.60
<i>2Vi</i>	0.14	0.31	0.42	0.50
<i>Mut</i>	0.06	0.14	0.20	0.24
<i>InH</i>	0.02	0.14	0.40	0.65
<i>PPI</i>	0.01	0.05	0.11	0.18

# Conclusion; fitting stochastic models

- Bayesian (pMCMC) or Frequentist (MIF)?
- Sampling from the posterior vs Exploring the likelihood surface?
- For both methods, a particle filter is required to evaluate the likelihood of stochastic models.

# Conclusion; fitting stochastic models

- Bayesian (pMCMC) or Frequentist (MIF)?
- Sampling from the posterior vs Exploring the likelihood surface?
- For both methods, a particle filter is required to evaluate the likelihood of stochastic models.

# Conclusion; fitting stochastic models

- Bayesian (pMCMC) or Frequentist (MIF)?
- Sampling from the posterior vs Exploring the likelihood surface?
- For both methods, a particle filter is required to evaluate the likelihood of stochastic models.

## Win + AoN = WoN

